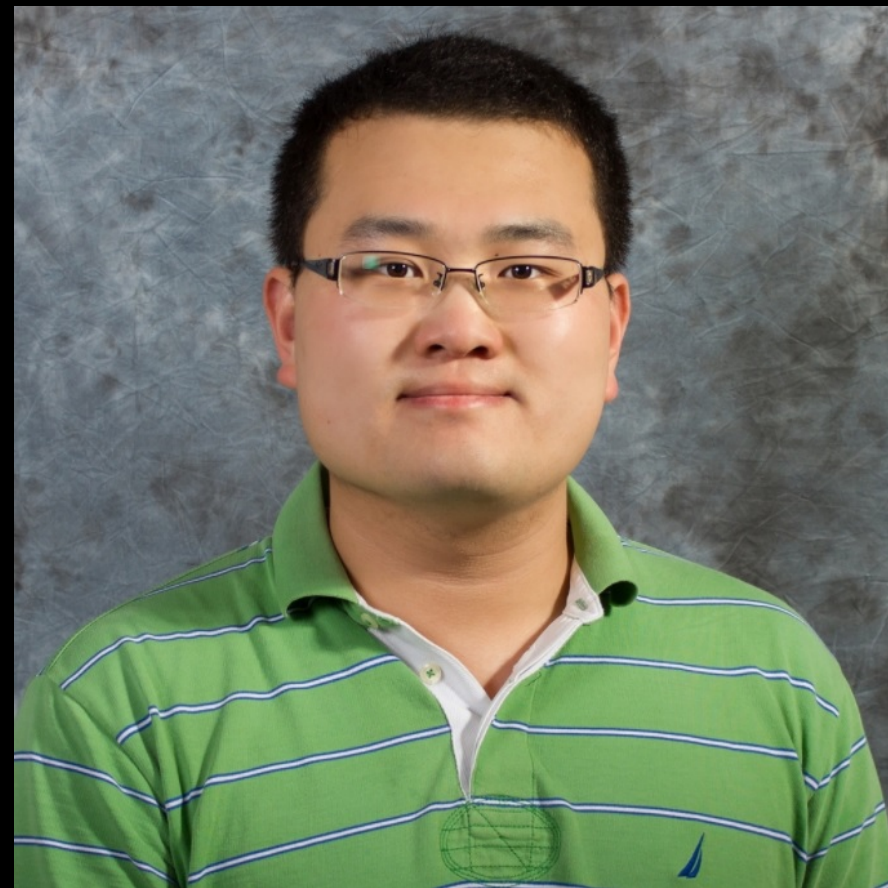


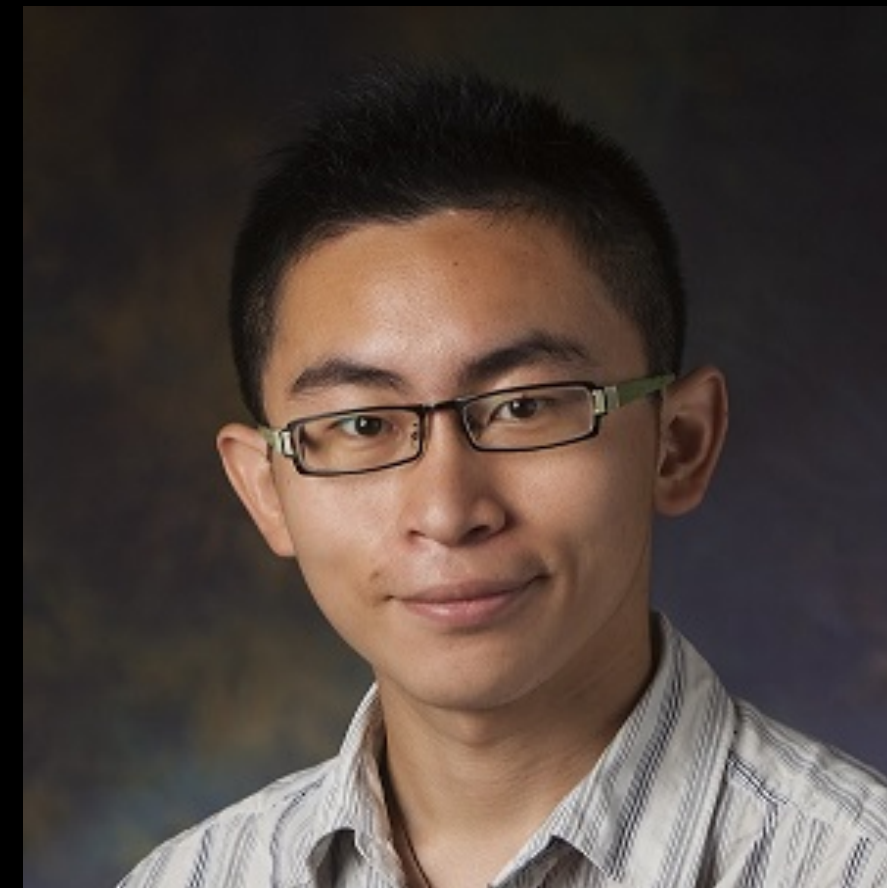
Flow-edge Guided Video Completion



Chen Gao
Virginia Tech



Ayush Saraf
Facebook



Jia-Bin Huang
Virginia Tech



Johannes Kopf
Facebook



Video Completion

Object removal



Input video

(green indicates the object to be removed)



Object-removed video

Video Completion

Stationary mask inpainting



Input video
(green indicates the occluded region)



Inpainted video

Frame Completion



Input frame
(green indicates the occluded region)



Inpainted frame

Frame Completion



Input video

(green indicates the object to be removed)

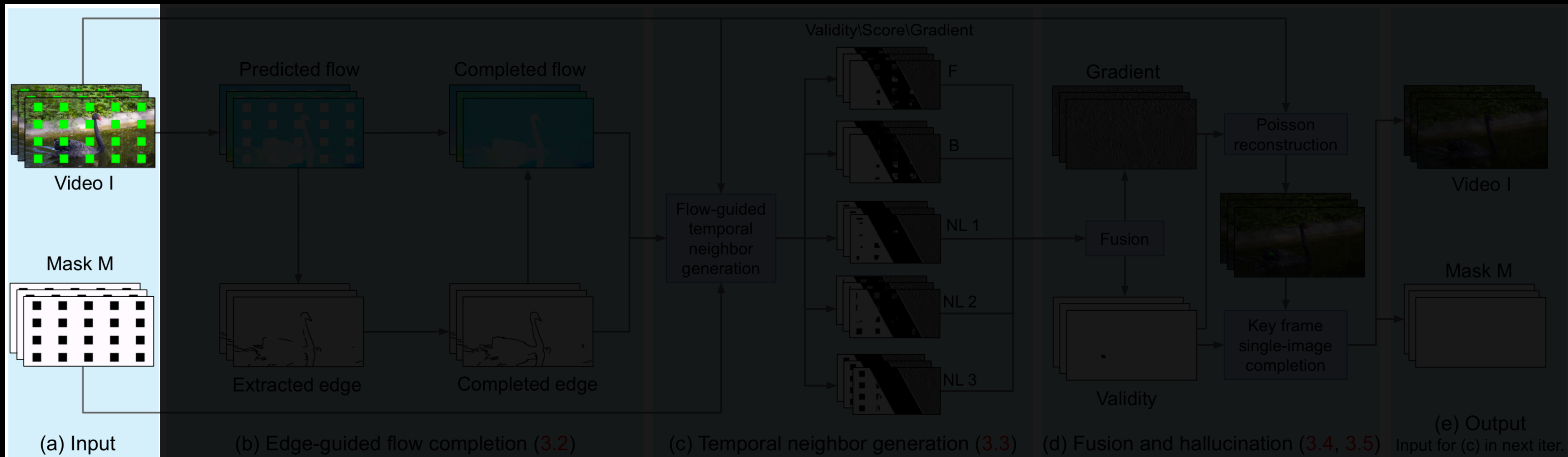


Object-removed video

(inpaint frame by frame)

Method

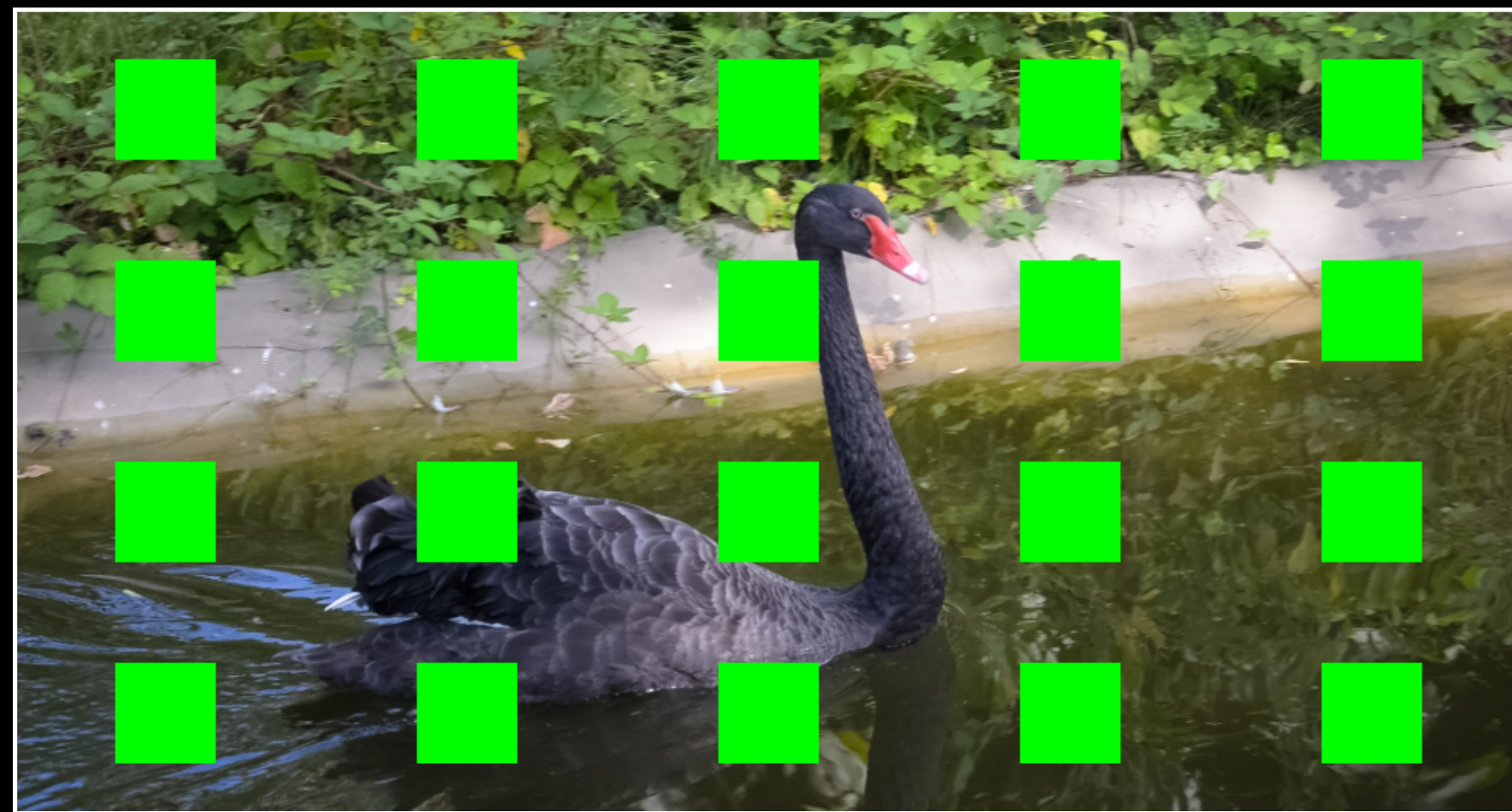
Overview



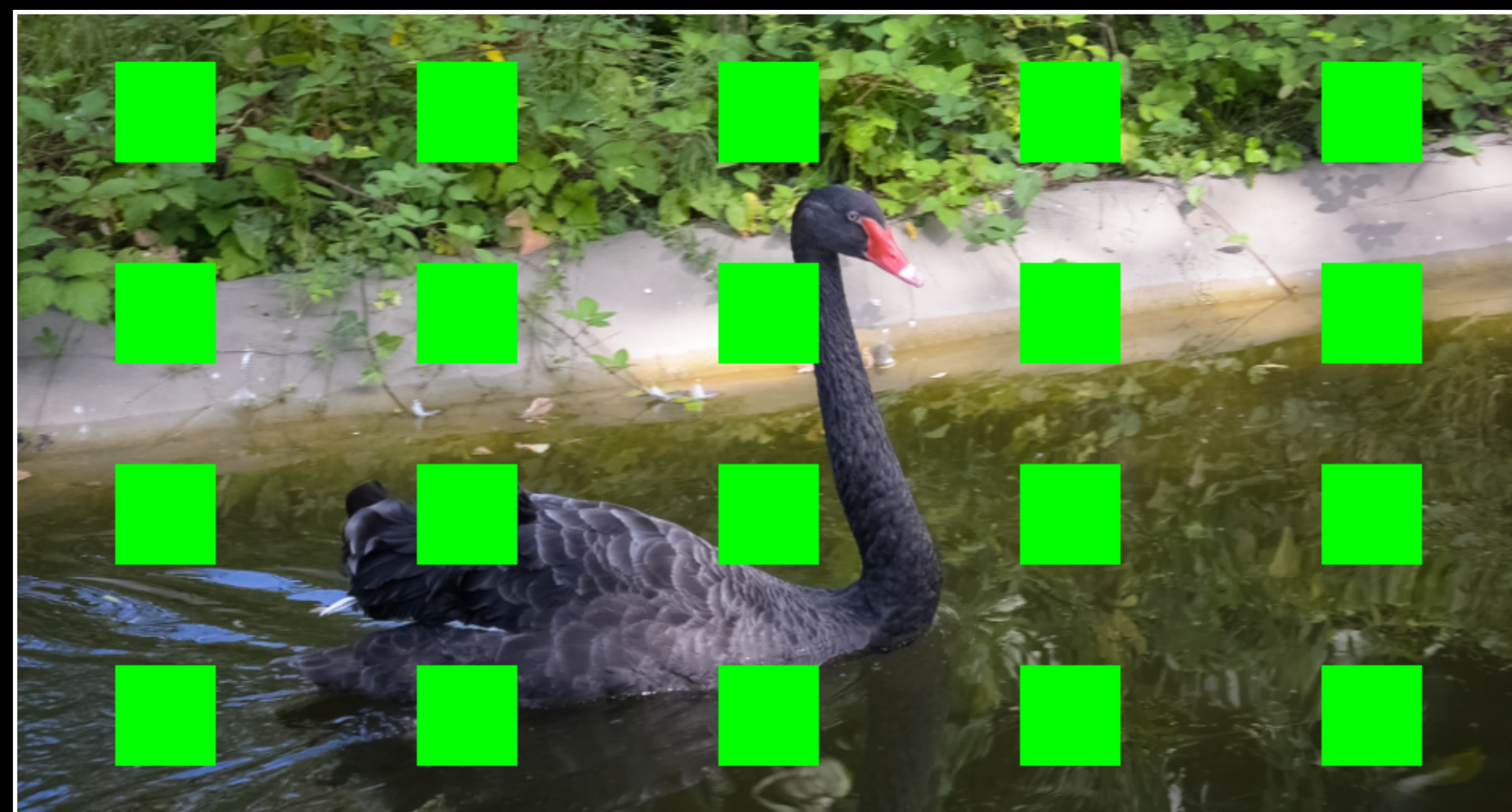
Flow completion

Color completion

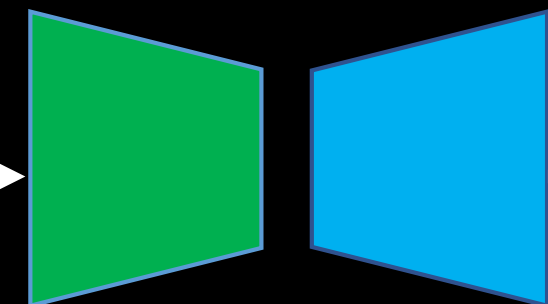
Flow Completion



Frame I_i



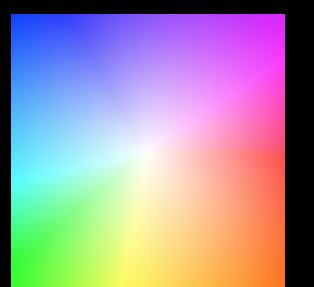
Frame I_j



FlowNet2

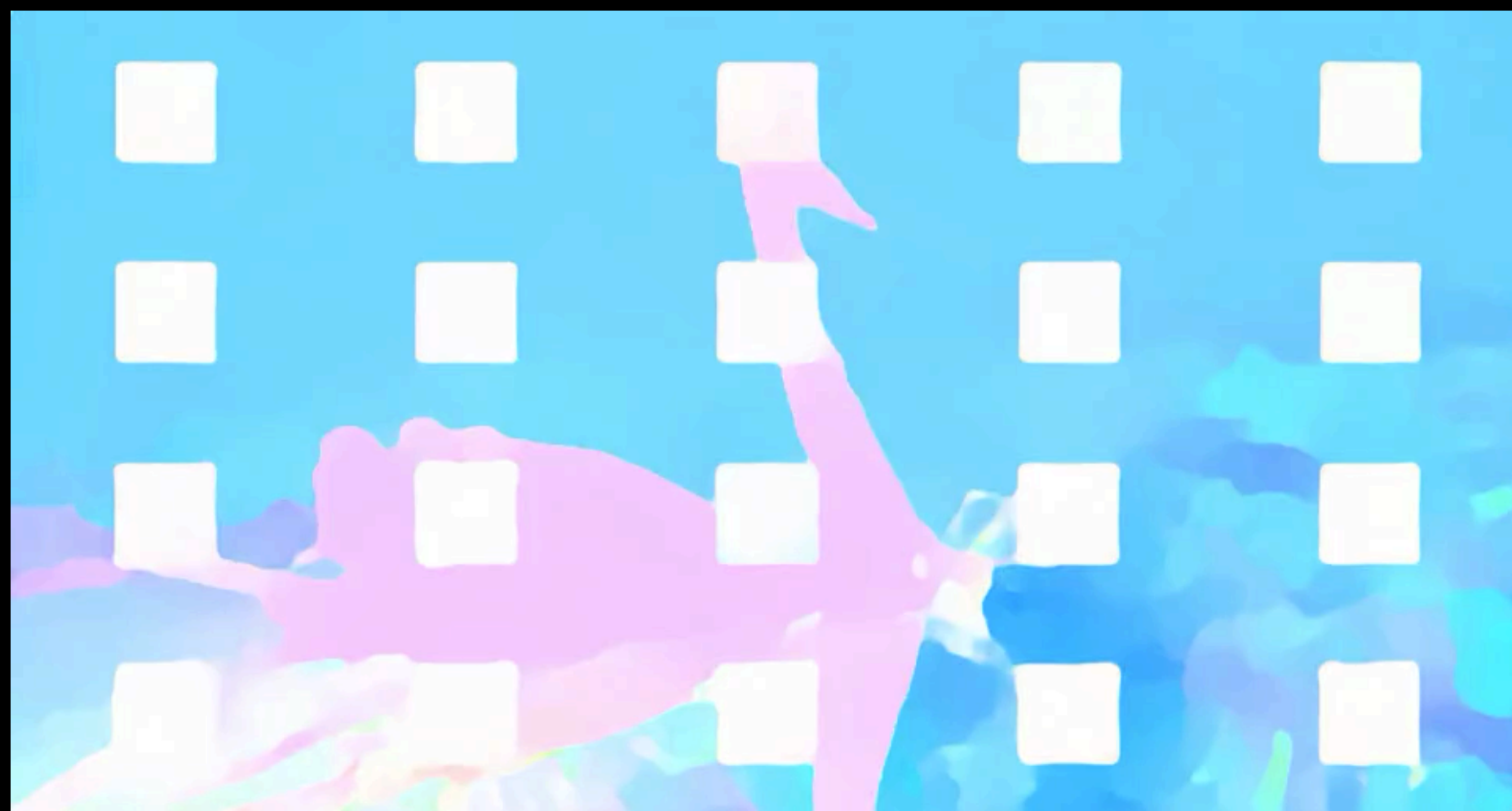


Flow $F_{i \rightarrow j}$

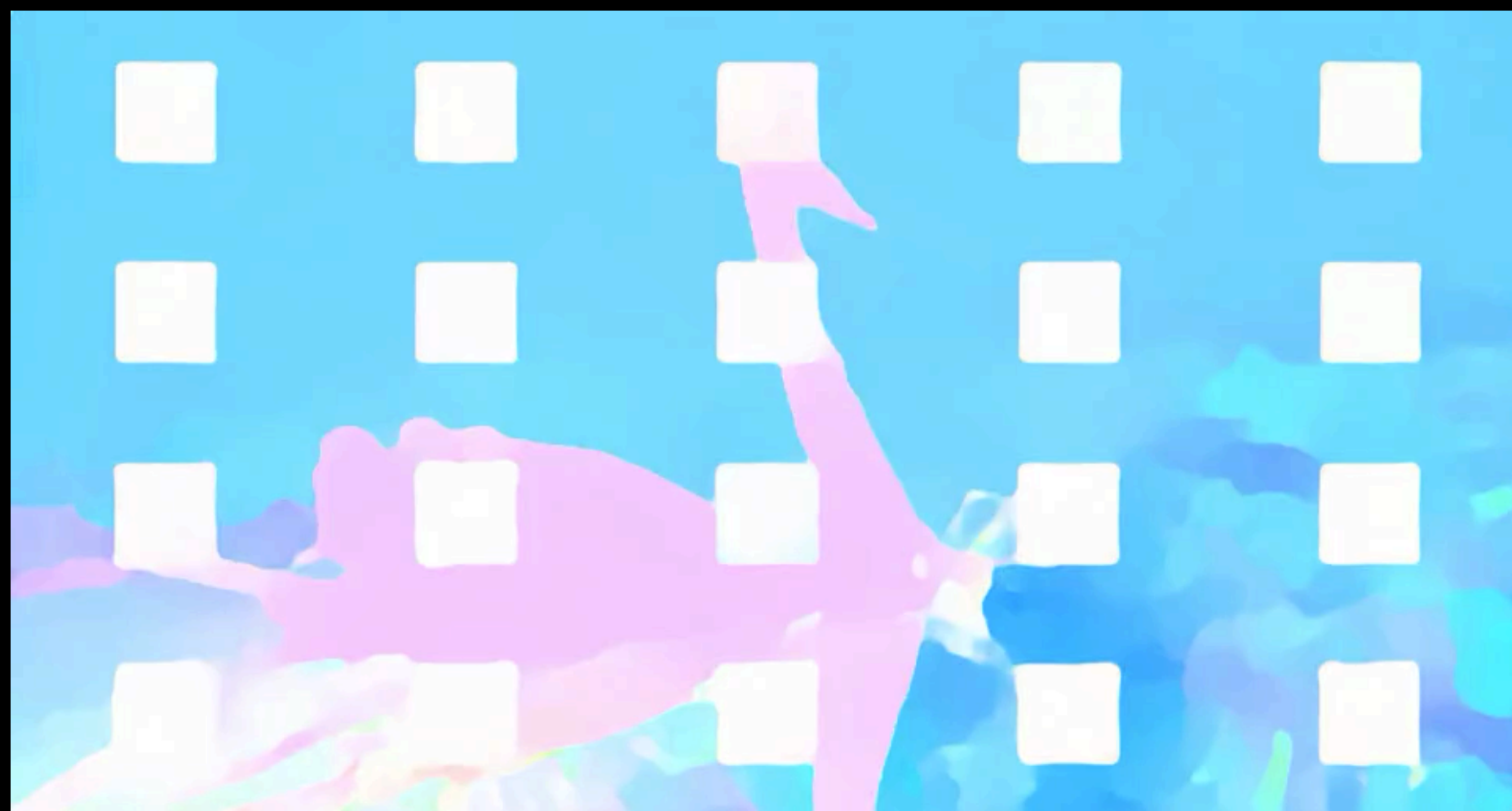


Flow field
color encoding

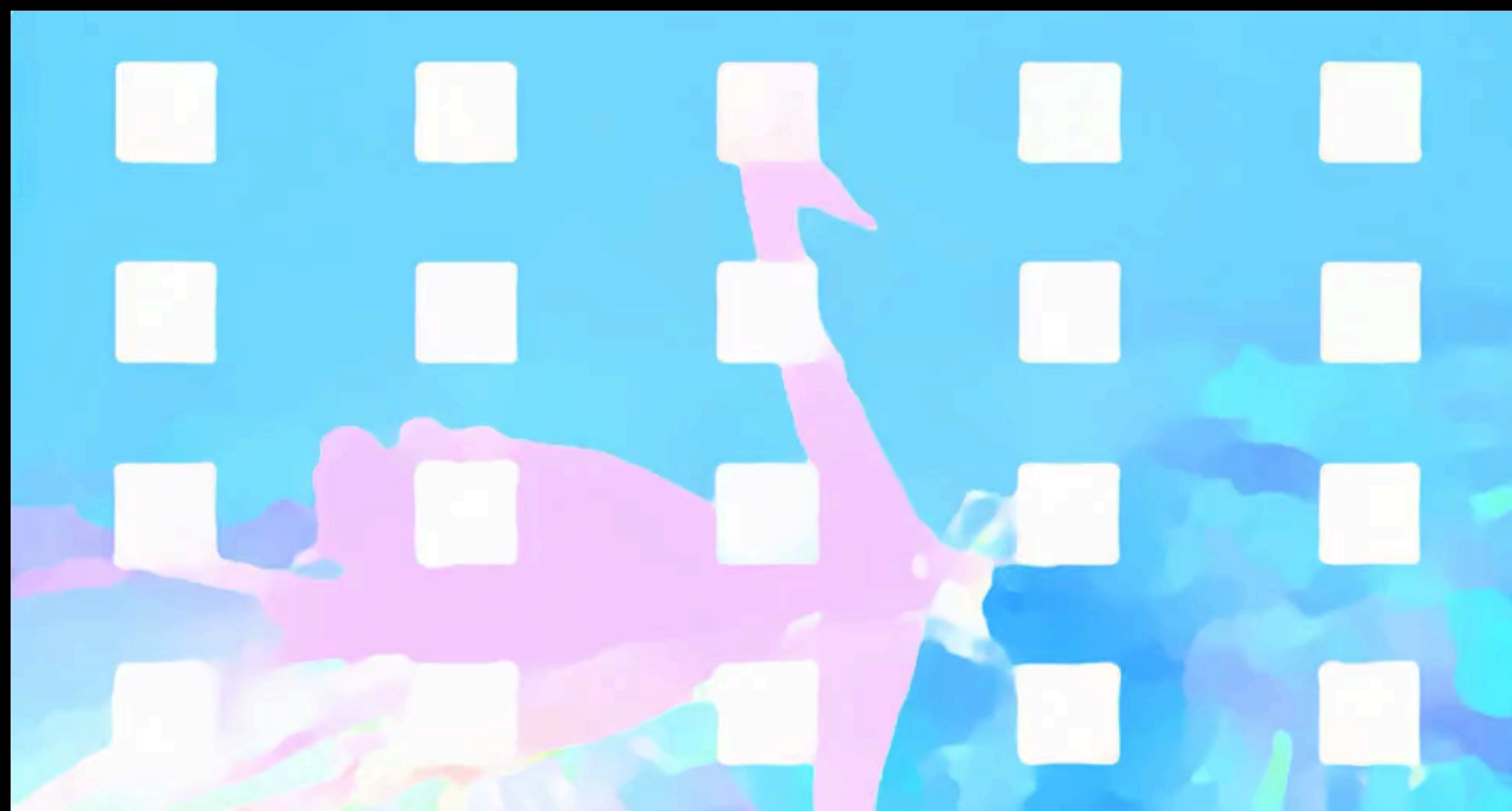
Flow Completion



Flow Completion



Flow Completion

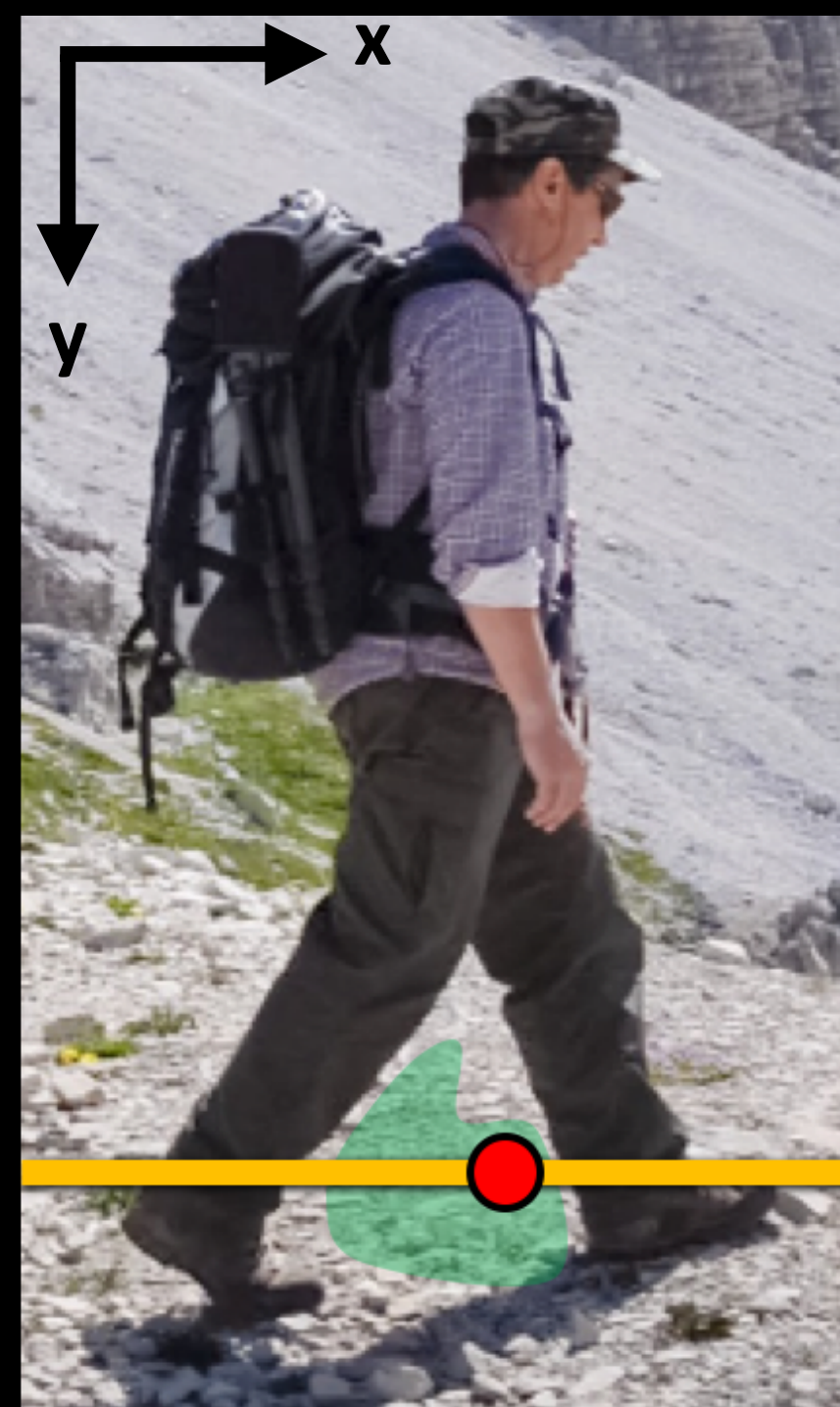


Color Completion

Find known temporal neighbor for each missing pixel



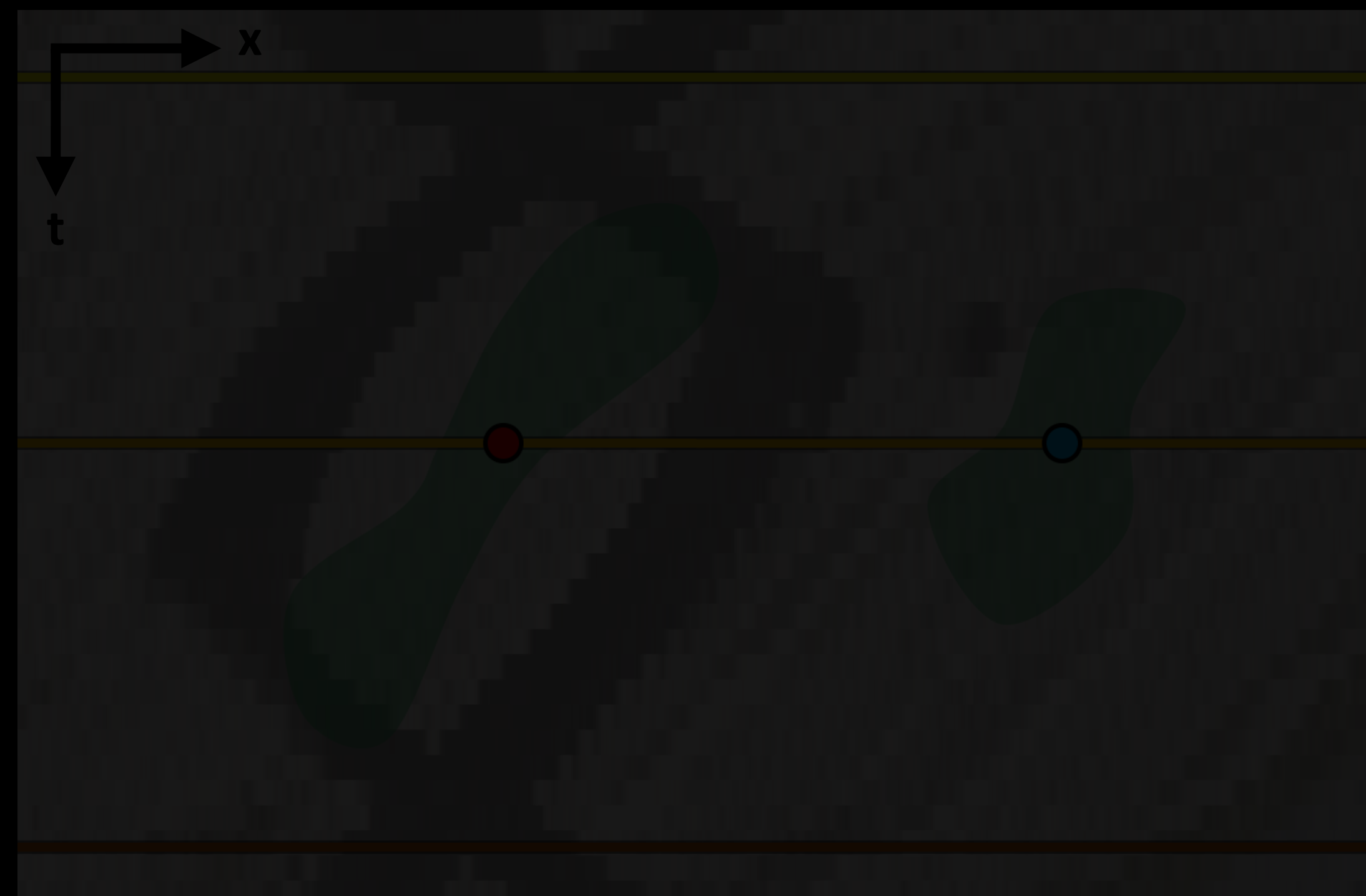
Early frame



Current frame



Later frame



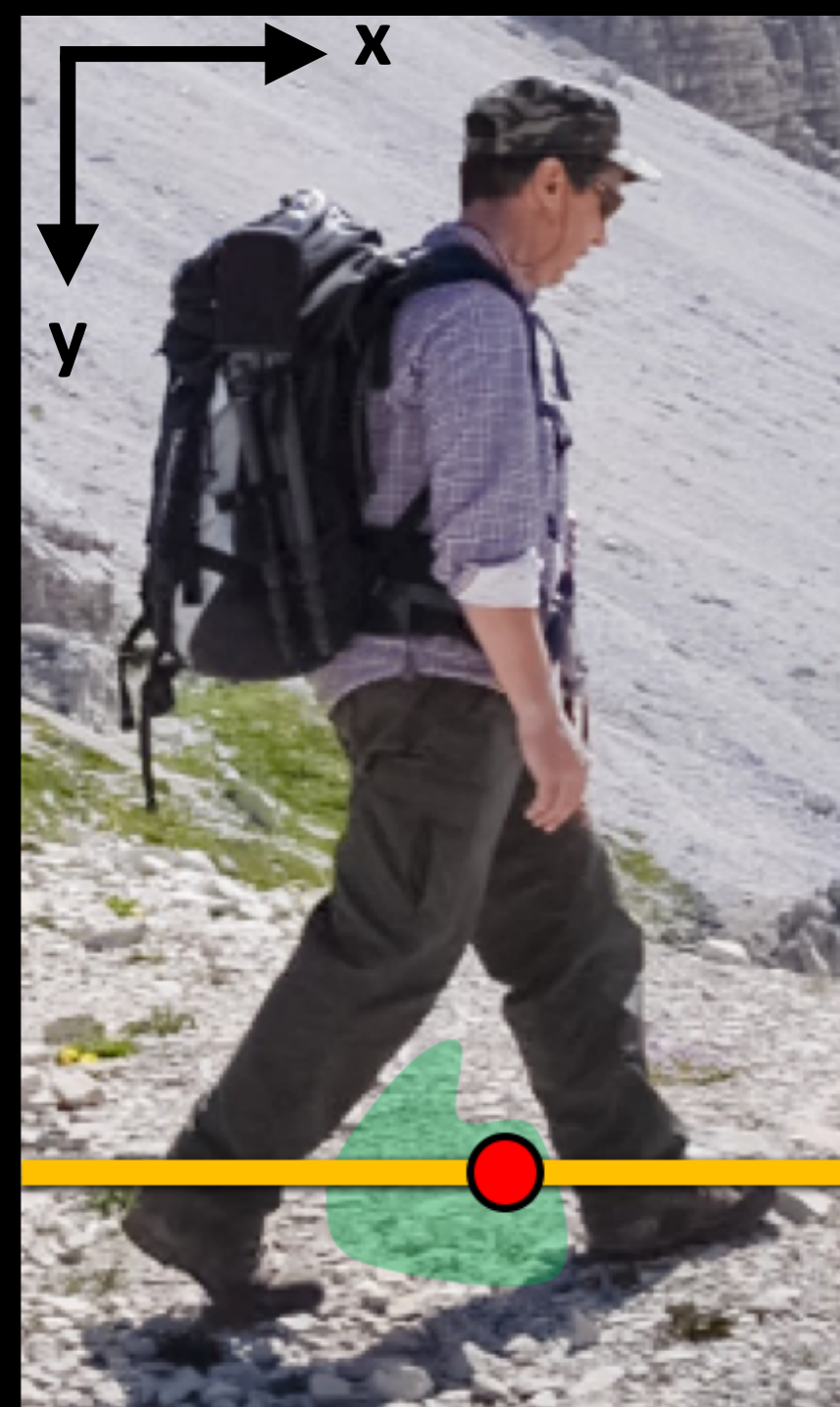
Space-time

Color Completion

Find known temporal neighbor for each missing pixel



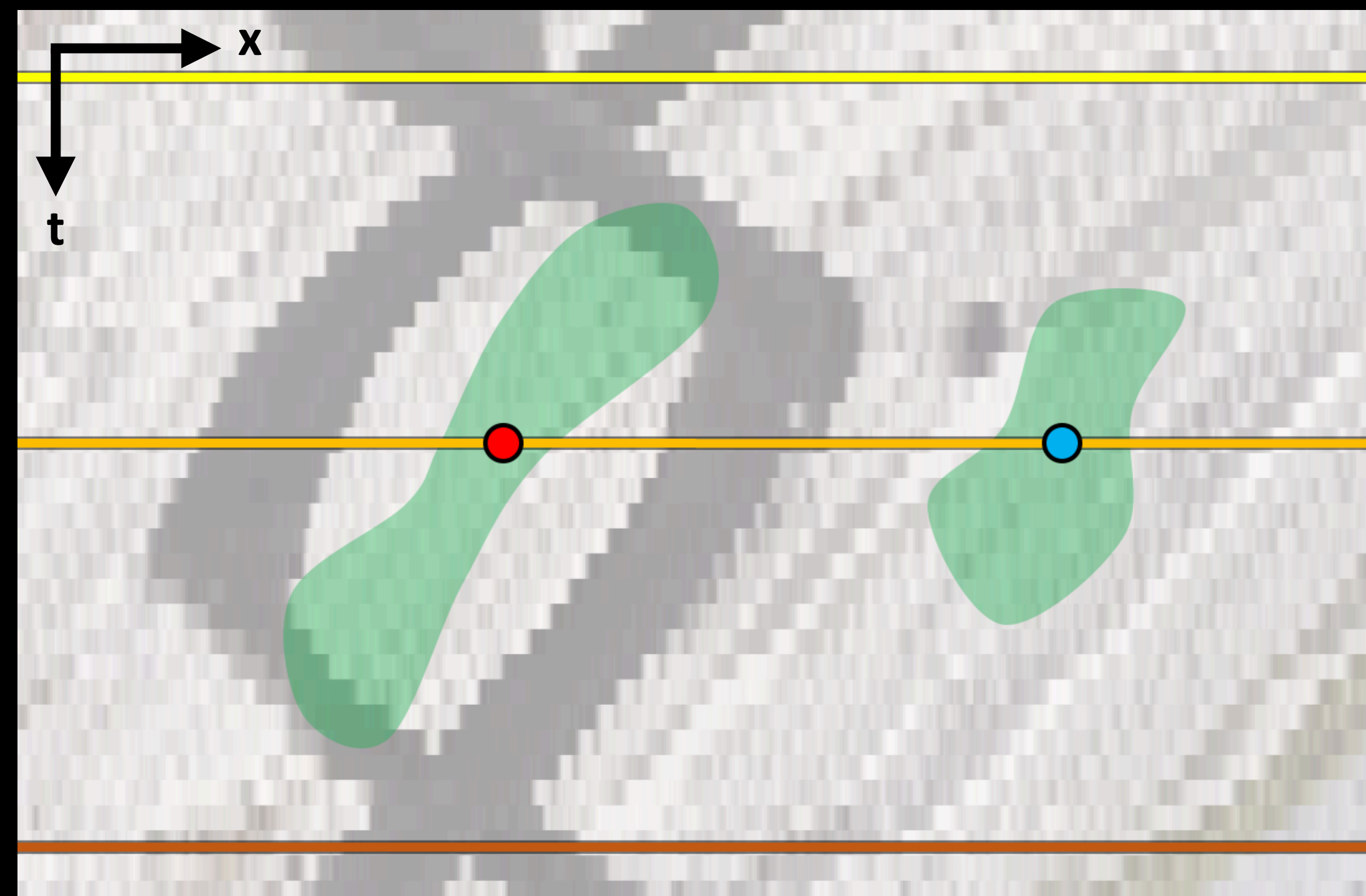
Early frame



Current frame



Later frame



Space-time

Color Completion

Find known temporal neighbor for each missing pixel



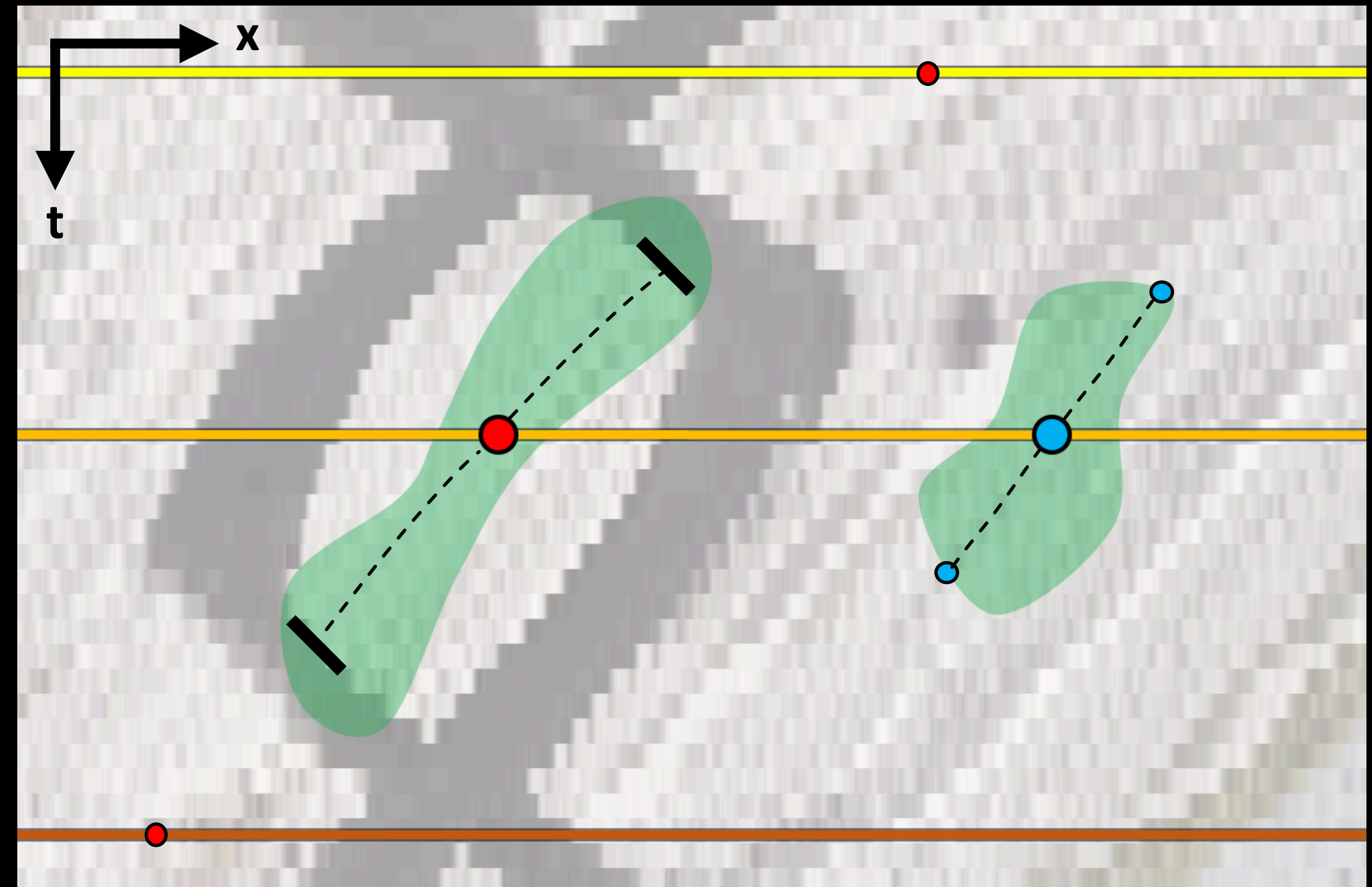
Early frame



Current frame



Later frame



Space-time

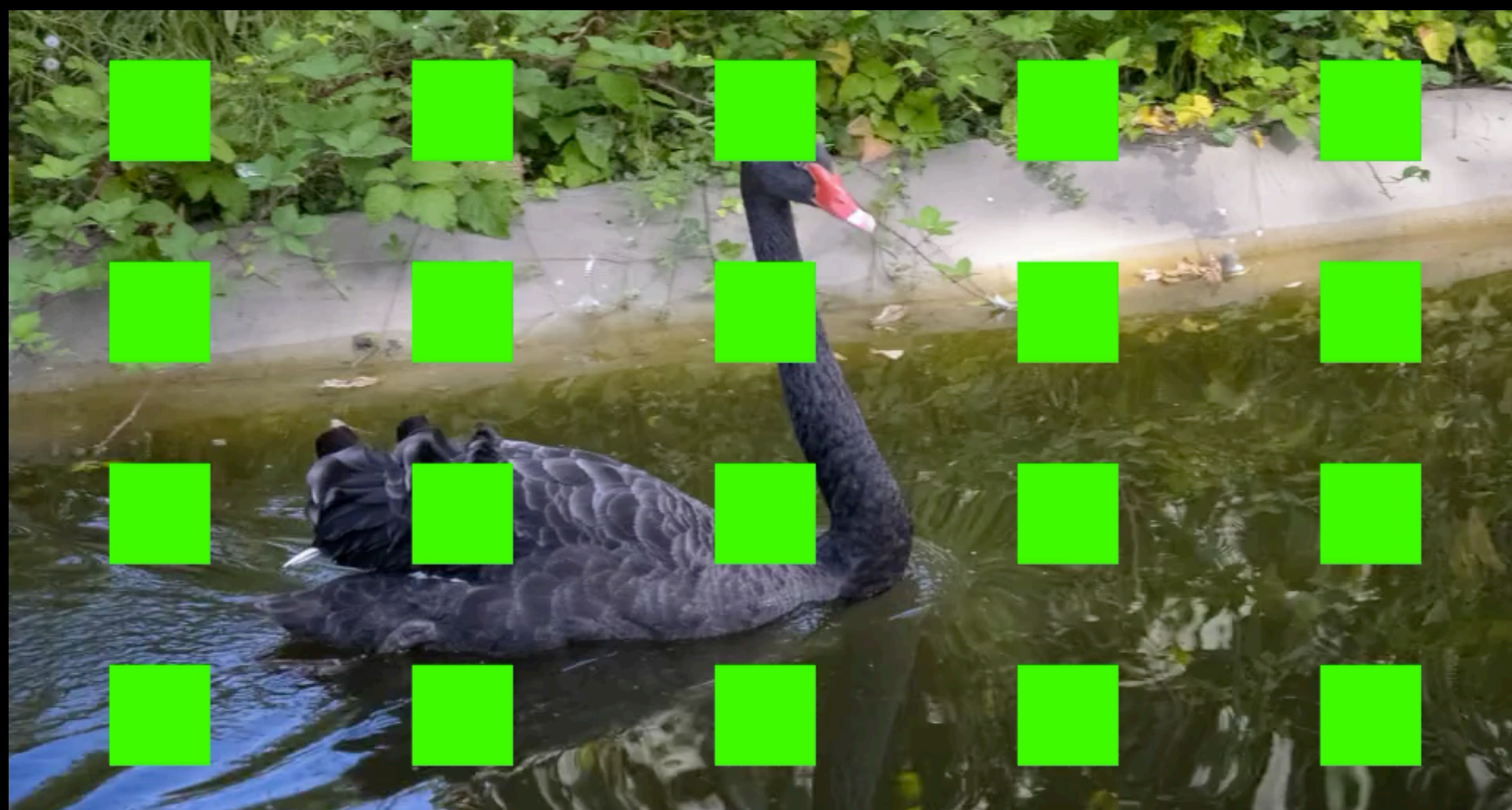
Non-local Flow Neighbors



Without non-local neighbors

With non-local neighbors

Color Completion

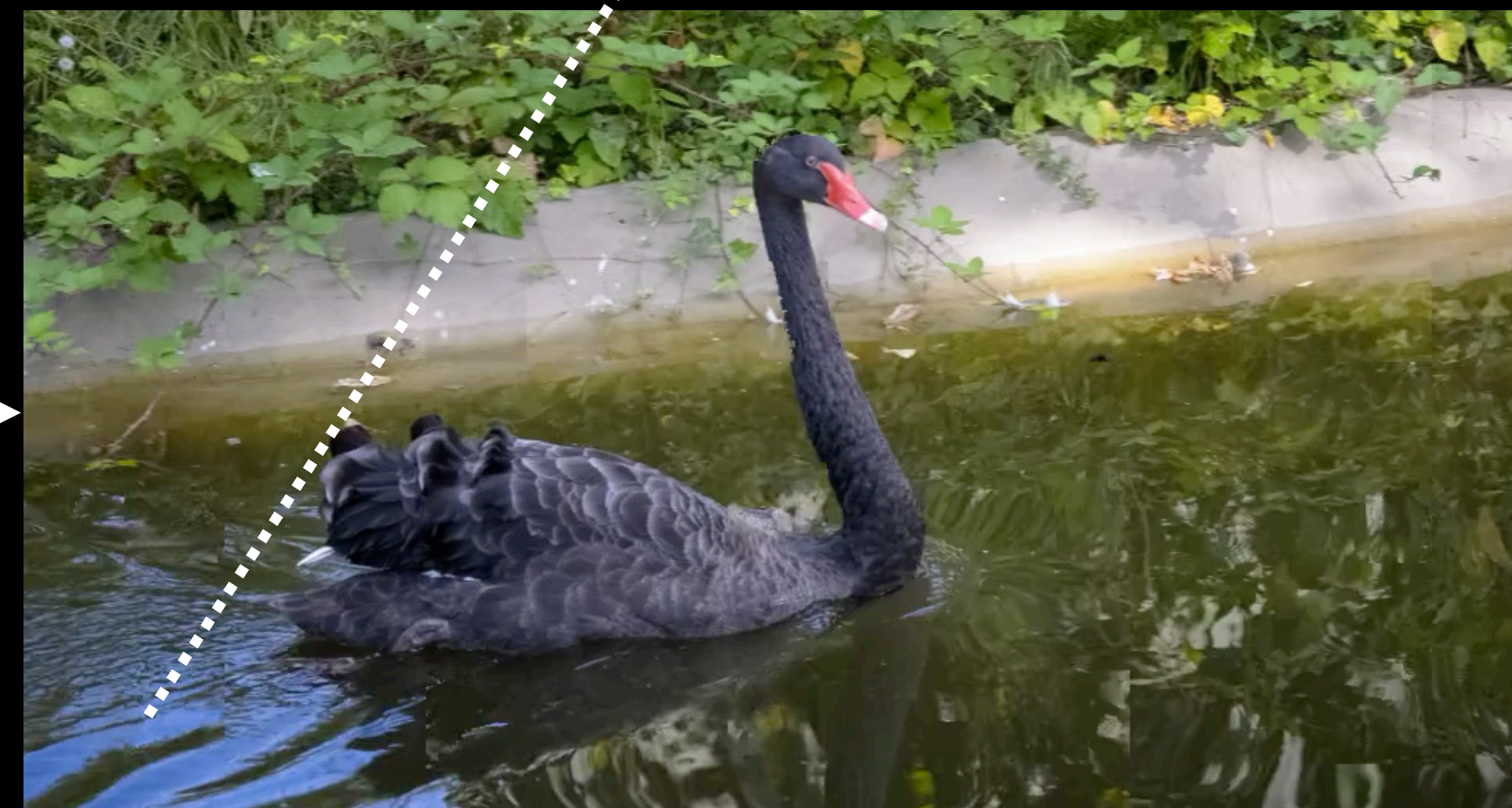


Input video

(green indicates missing region)



Color domain

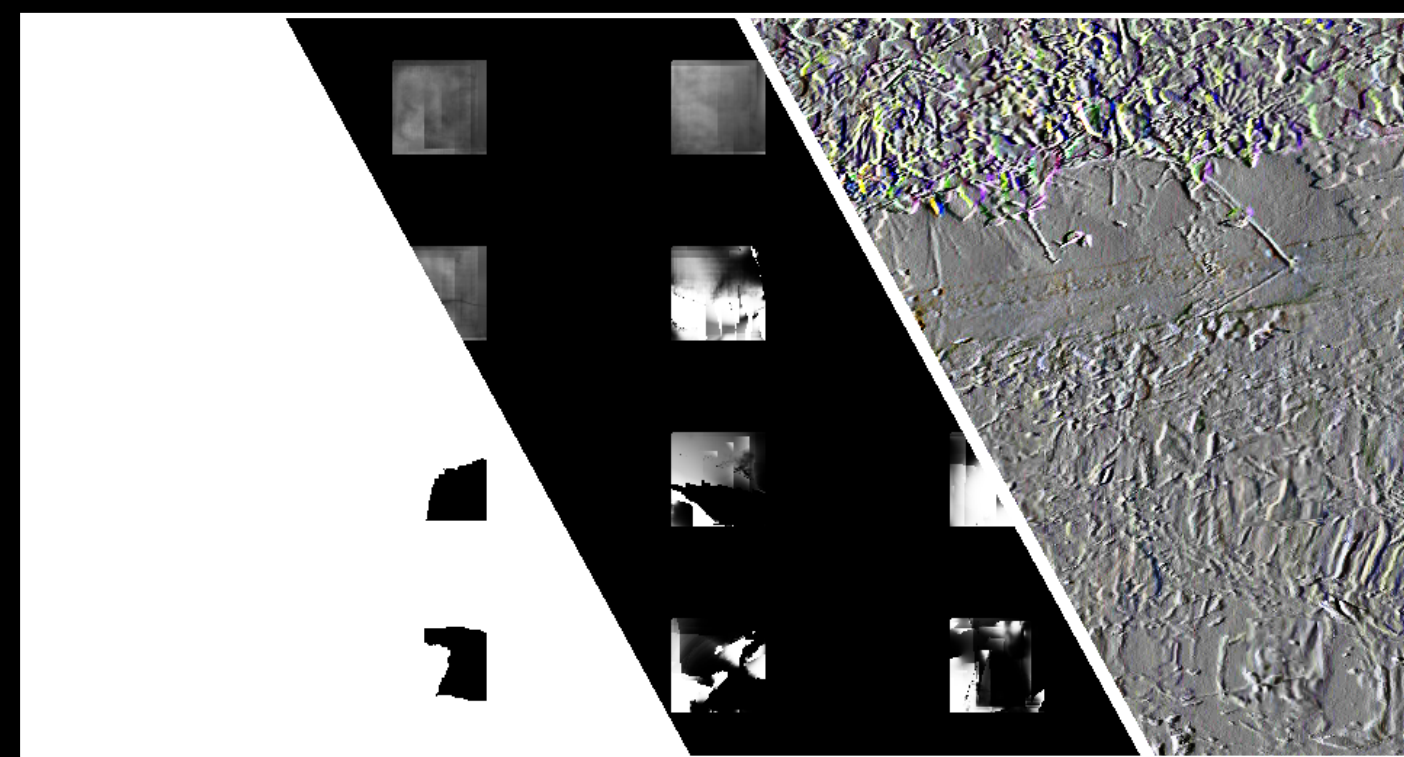


Completed video

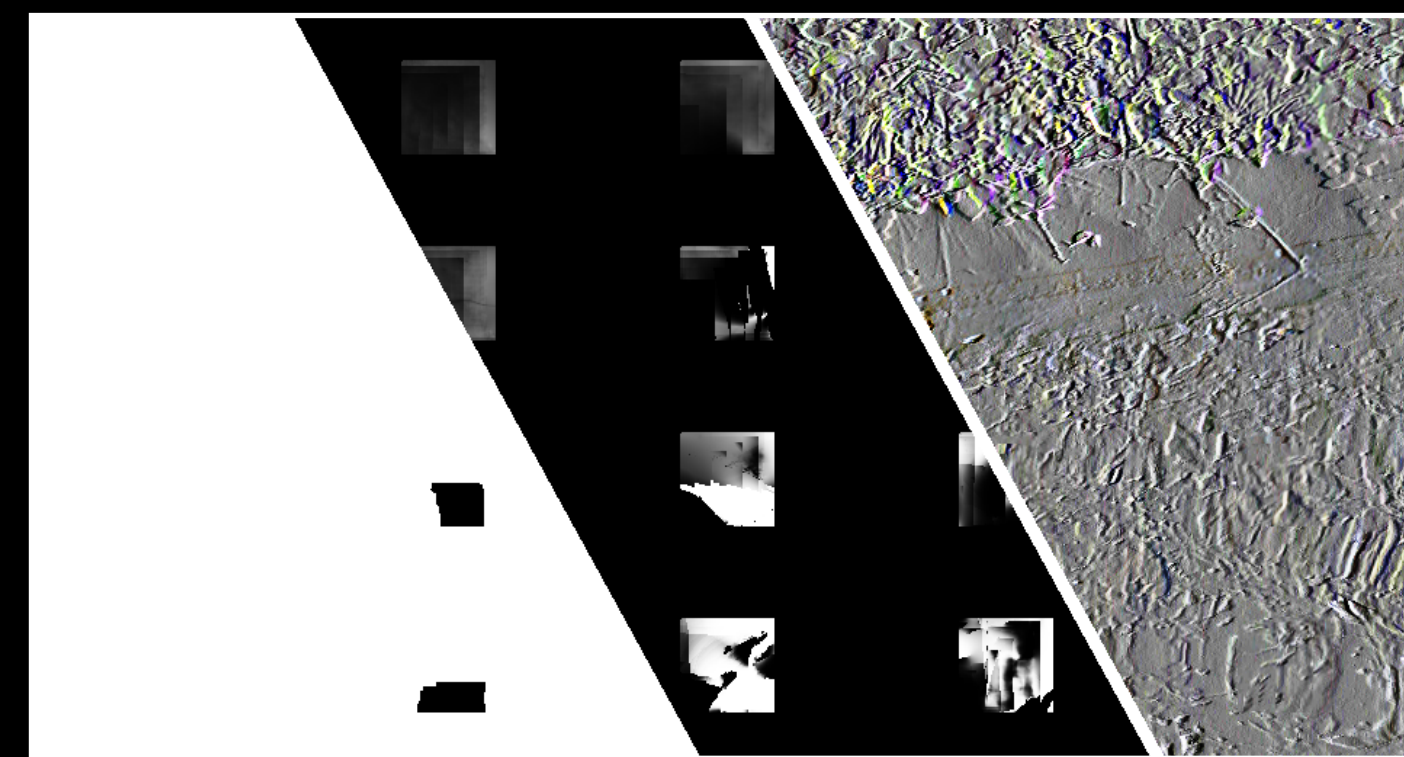


Color Completion

Obtain local and non-local temporal neighbors as candidates

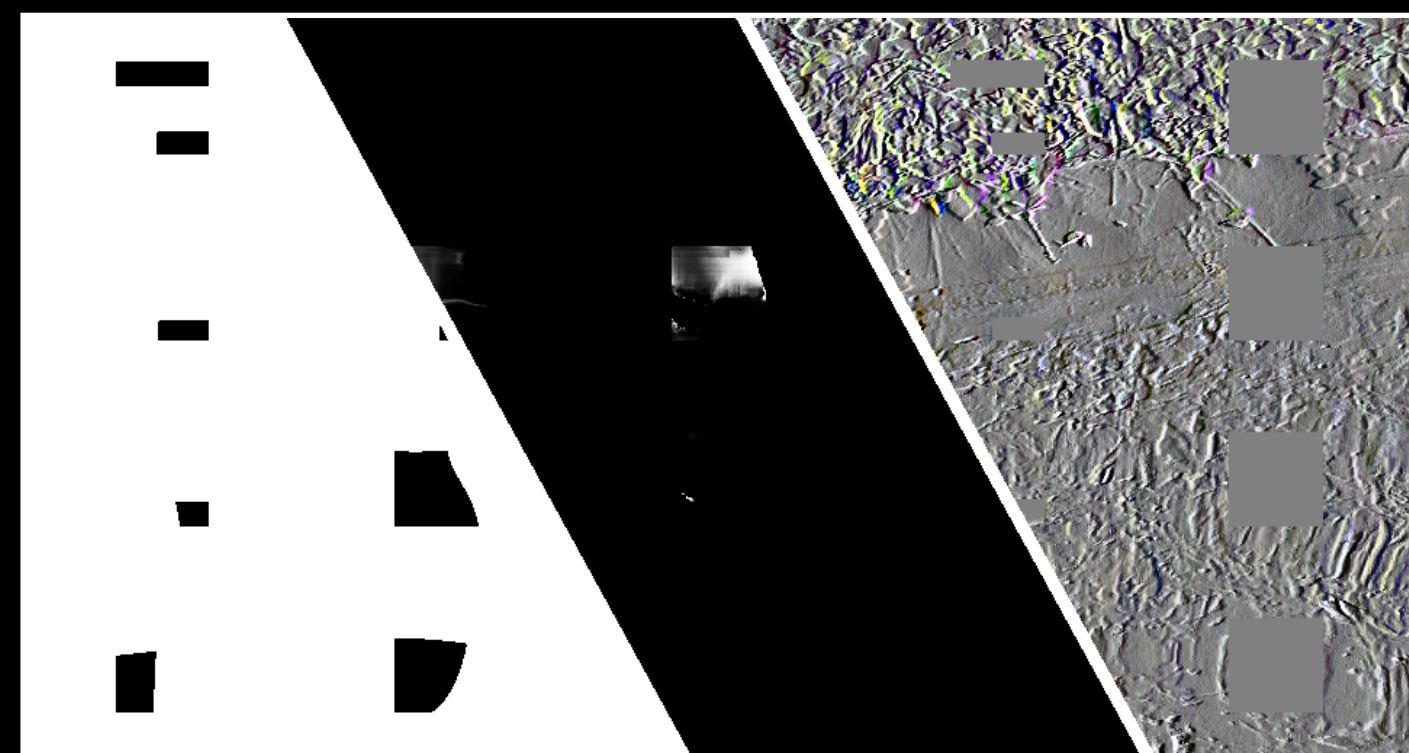


Forward flow neighbor

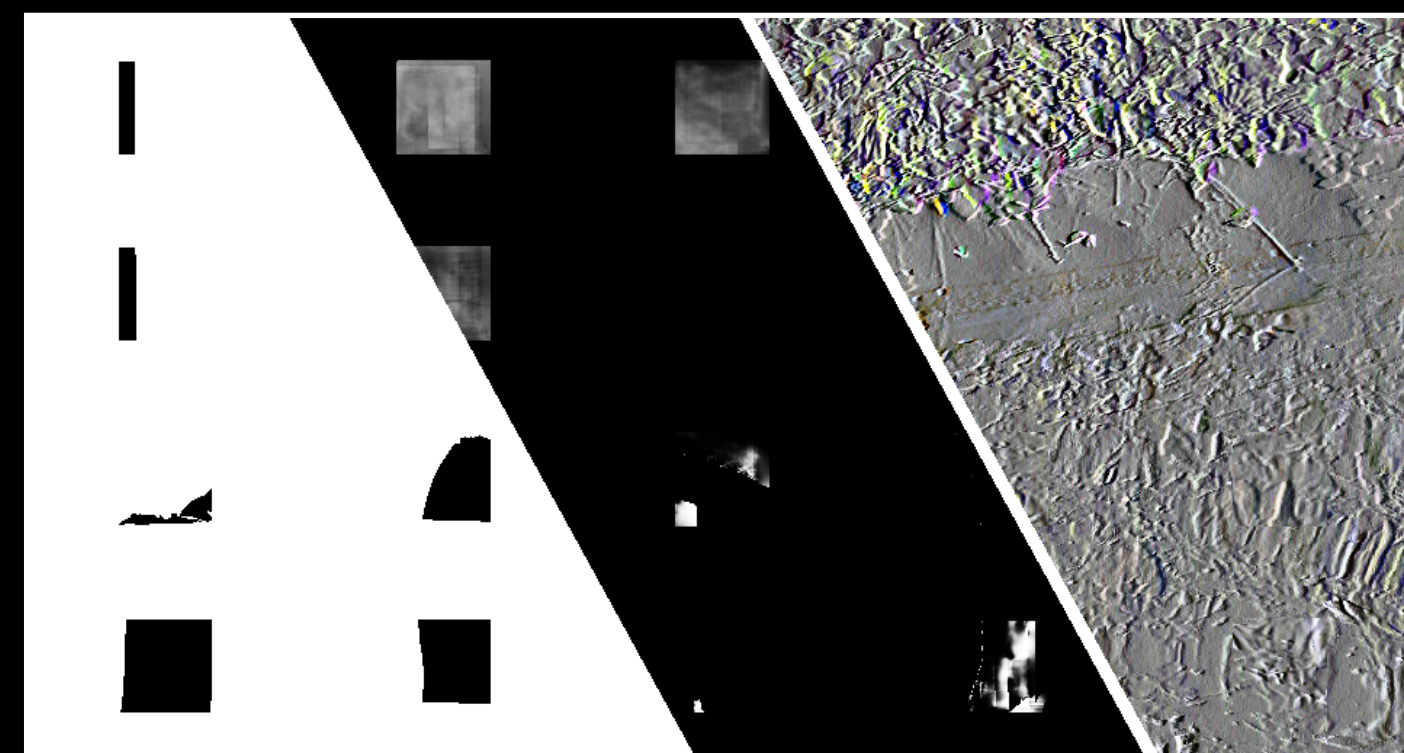


Backward flow neighbor

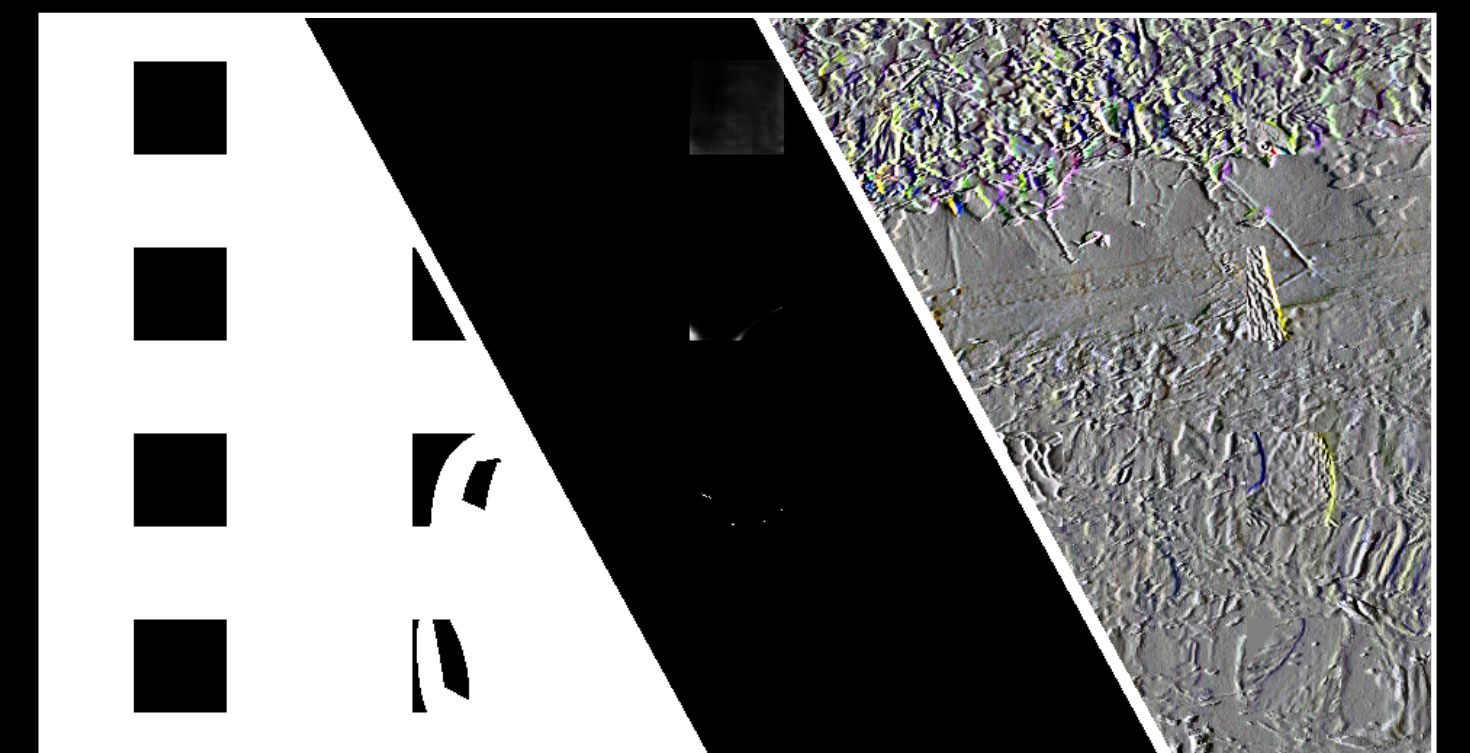
Validity \ Score \ Gradient



Non-local flow neighbor 1



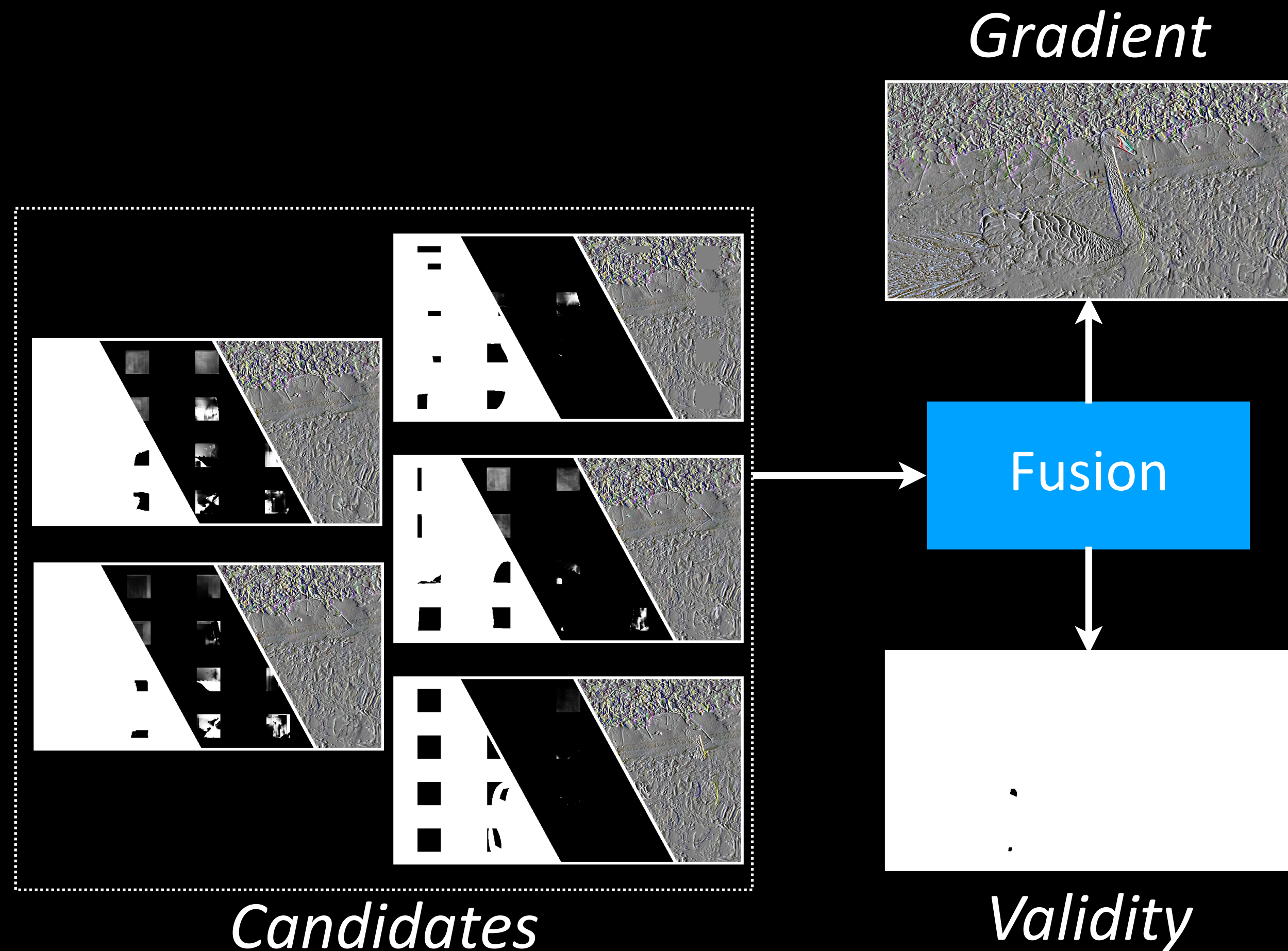
Non-local flow neighbor 2



Non-local flow neighbor 3

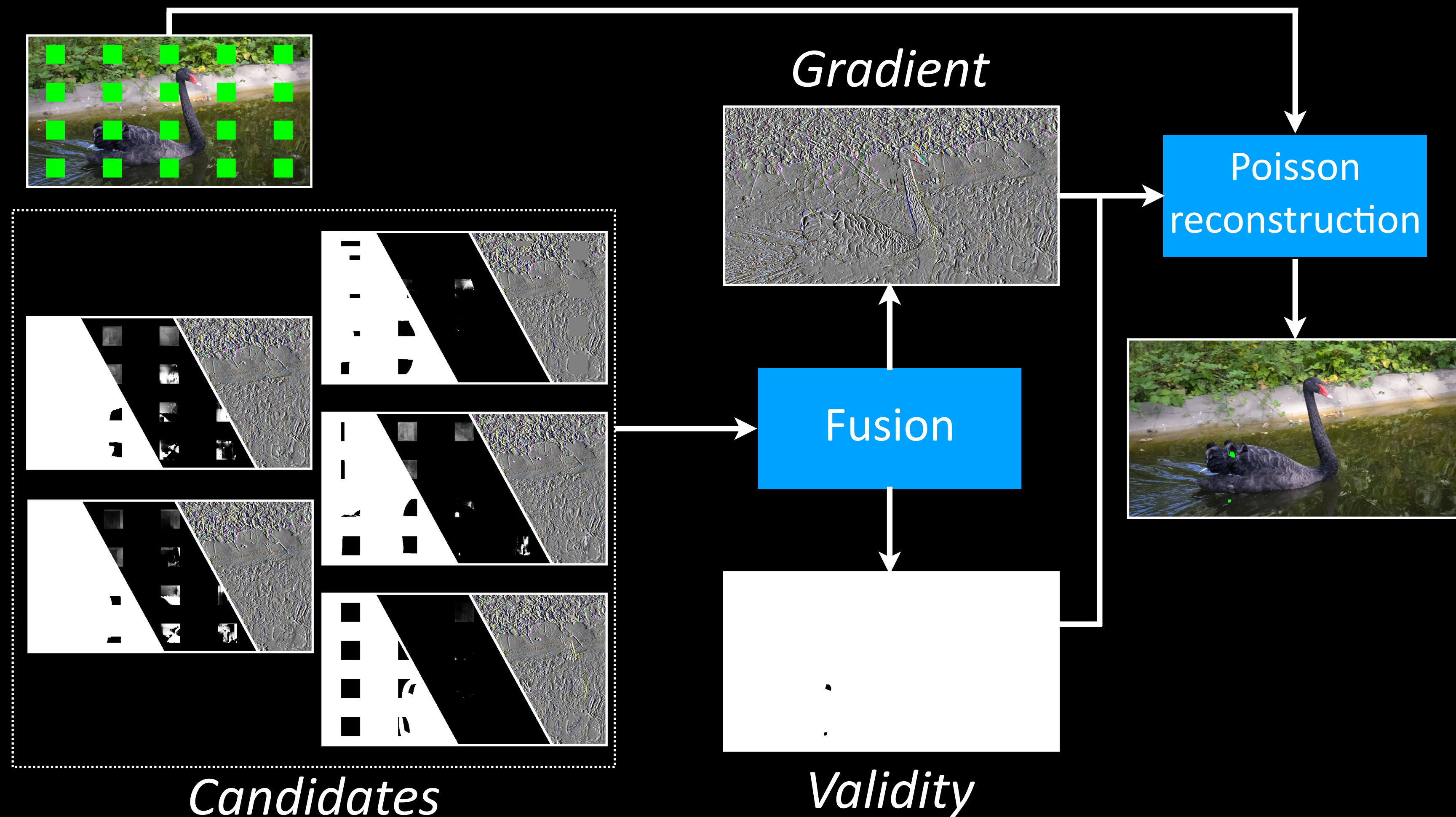
Color Completion

Fuse candidates in the gradient domain using confidence-weighted average



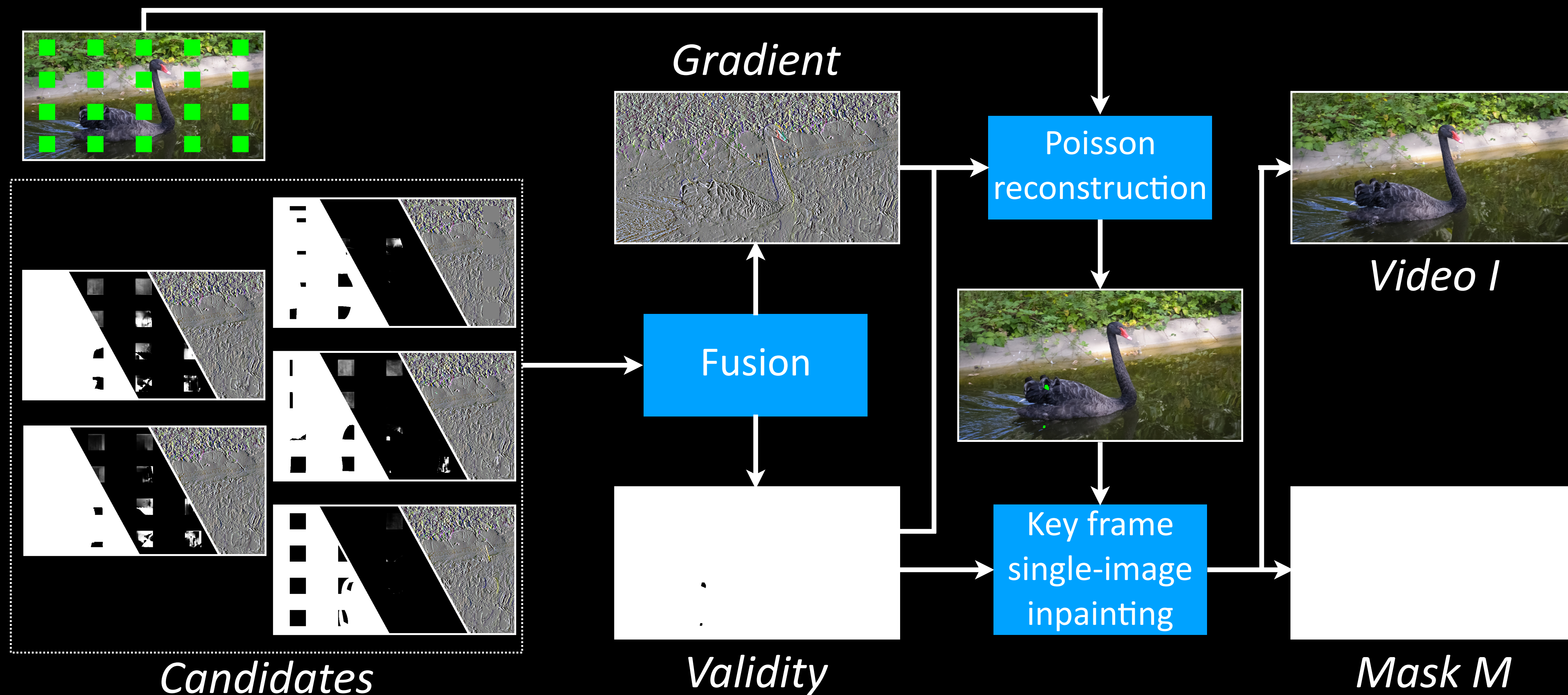
Color Completion

Reconstruct images by Poisson reconstruction



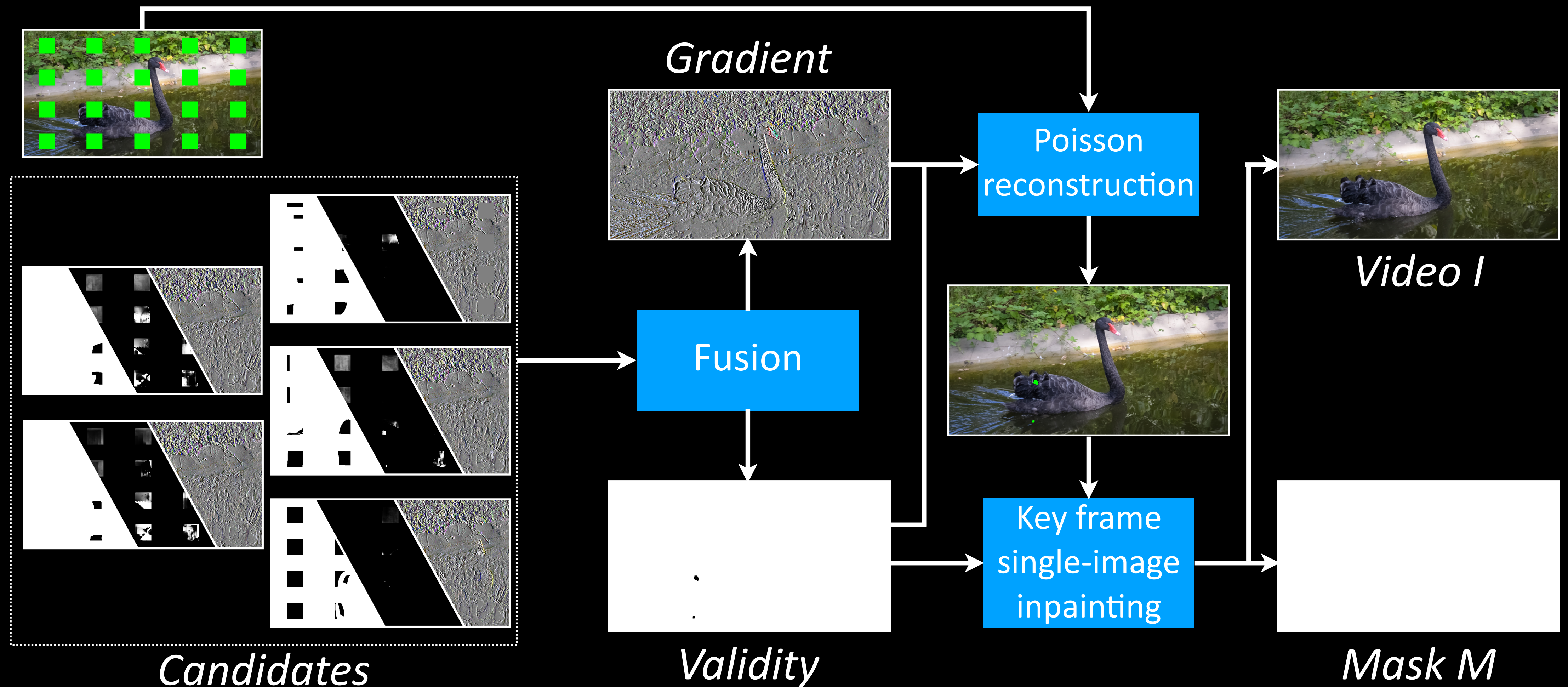
Color Completion

Pick a frame with most missing pixels and fill with spatial inpainting

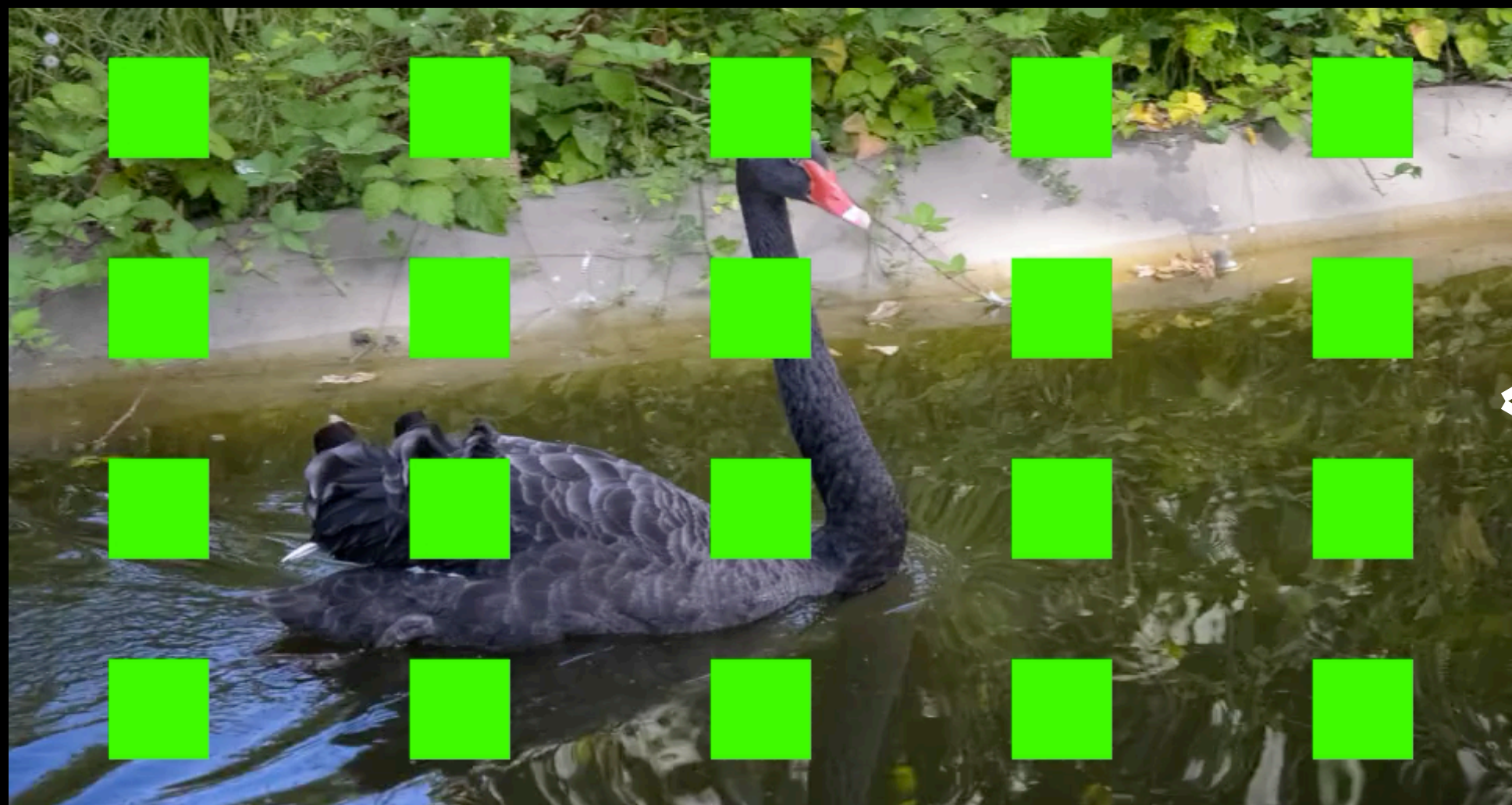


Color Completion

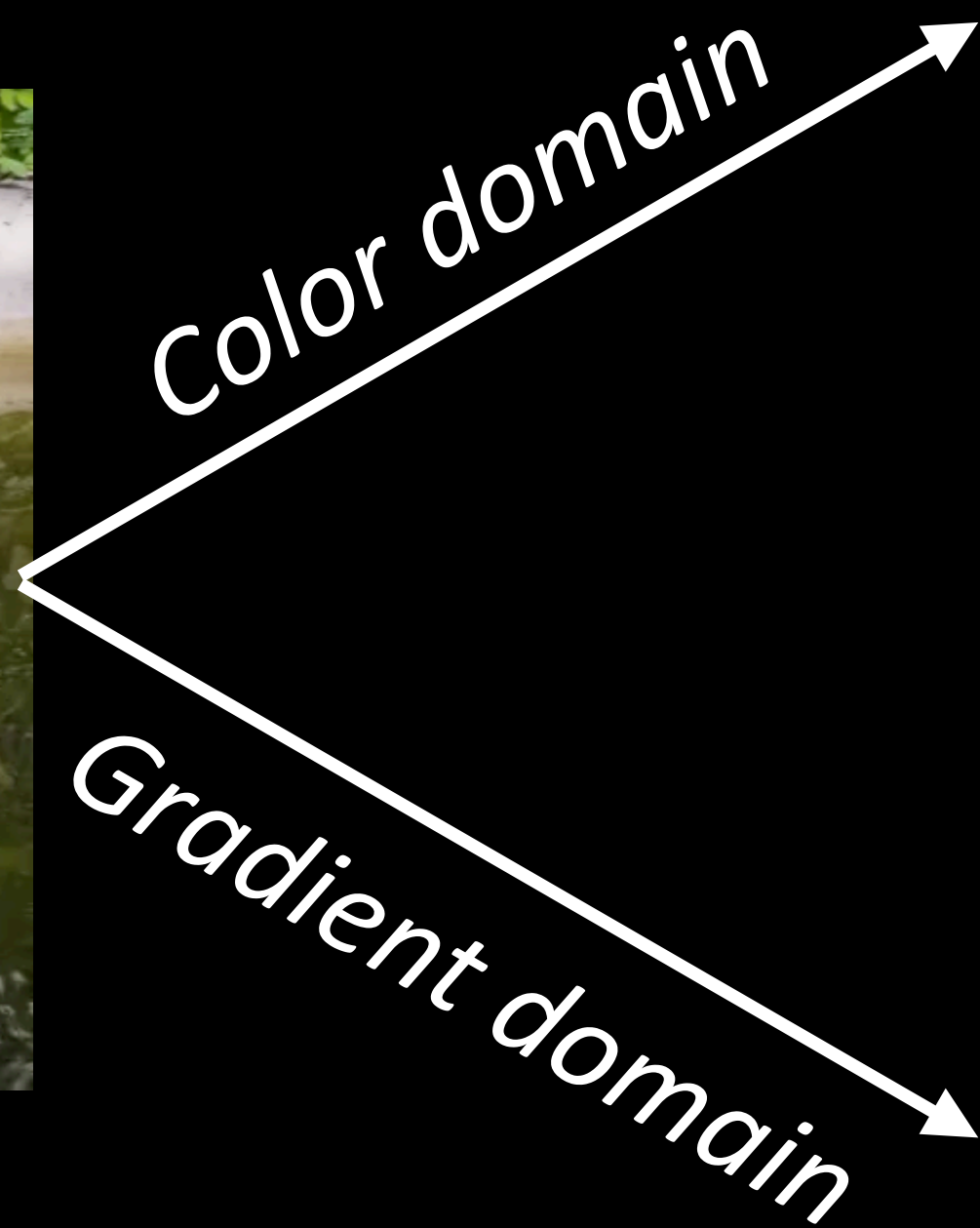
Pass the results into the next iteration until there is no missing pixel



Video Completion



Input video
(green indicates missing region)



Completed video

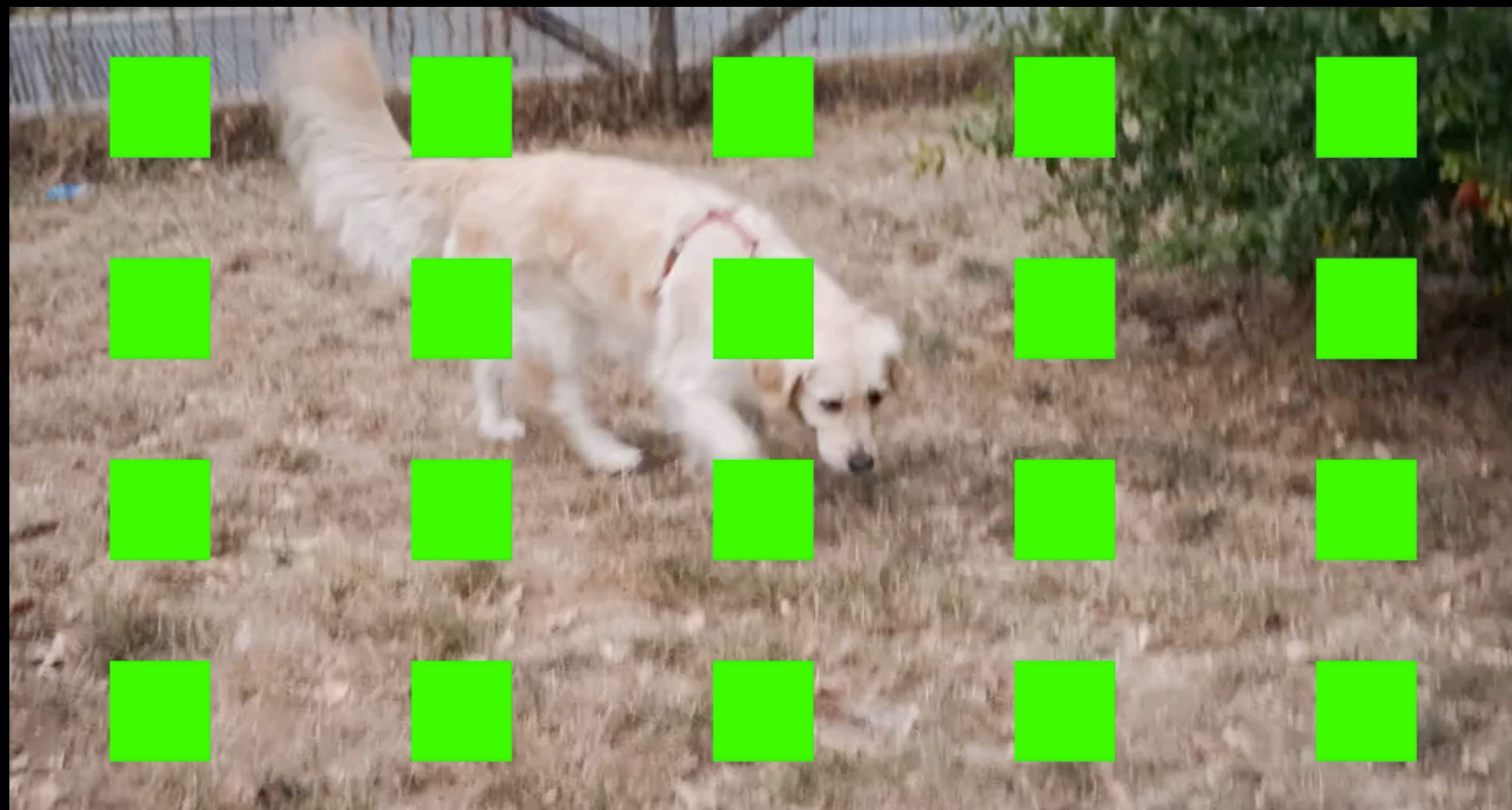
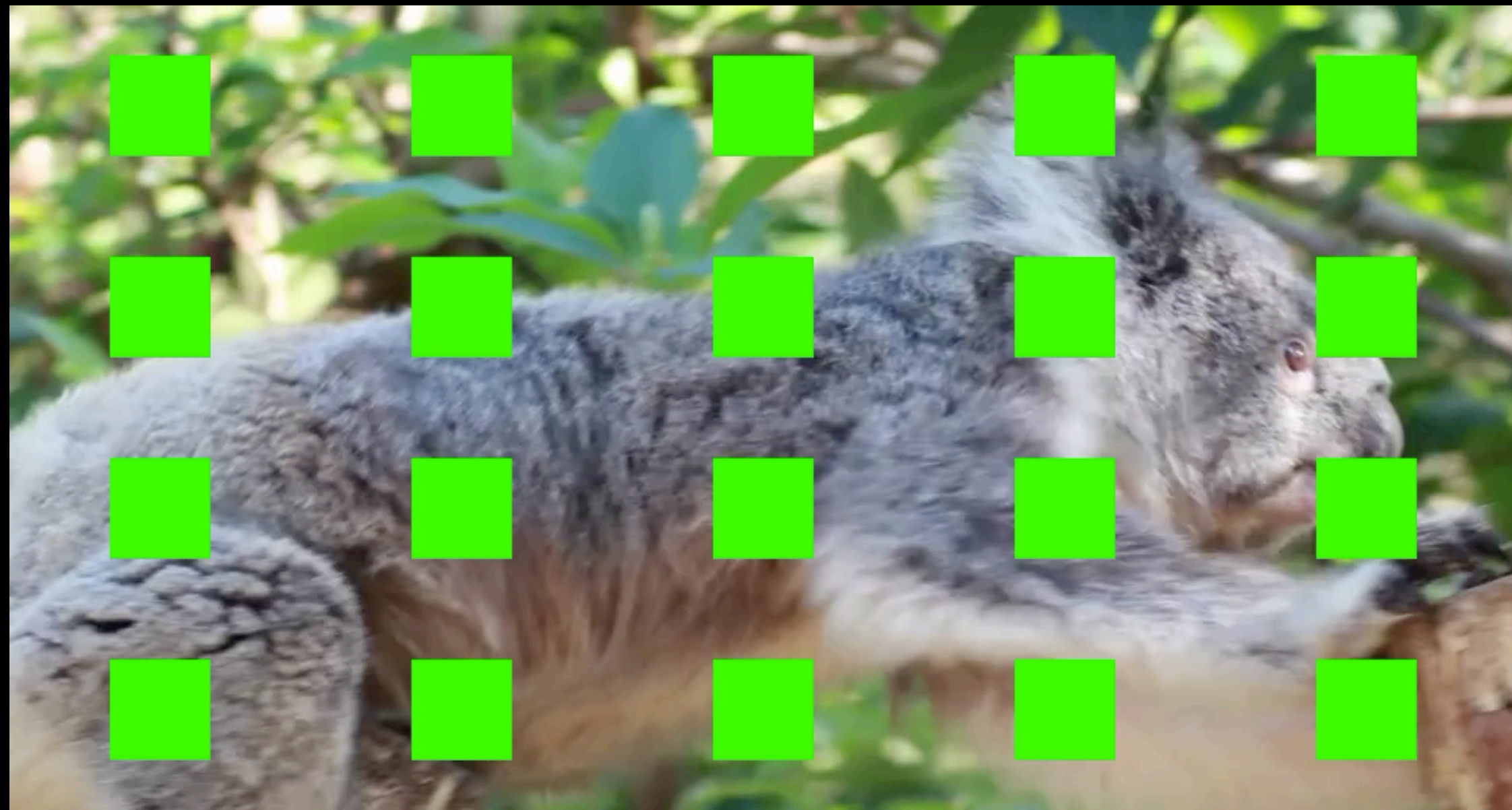
Color



Gradient



Results



Input video

(green indicates missing region)

Completed video



Input video
(green indicates missing region)

Completed video



Input video

Completed video

(green indicates the object to be removed)



Input video

(green indicates the object to be removed)

Completed video

Quantitative evaluation

	720 × 384 resolution					
	Stationary masks			Object masks		
	PSNR ↑	SSIM ↑	LPIPS ↓	PSNR ↑	SSIM ↑	LPIPS ↓
Kim <i>et al.</i>	25.19	0.8229	0.301	28.07	0.8673	0.283
Newson <i>et al.</i>	27.50	0.9070	<u>0.067</u>	32.65	0.9648	0.023
Xu <i>et al.</i>	27.69	0.9264	0.077	<u>39.67</u>	<u>0.9894</u>	<u>0.008</u>
Lee <i>et al.</i>	28.47	0.9170	0.111	35.76	0.9819	0.021
Huang <i>et al.</i>	28.72	0.9256	0.070	34.64	0.9725	0.018
Oh <i>et al.</i>	<u>30.28</u>	<u>0.9279</u>	0.082	33.78	0.9630	0.058
Ours	31.38	0.9592	0.042	42.72	0.9917	0.007

Flow-edge Guided Video Completion

Piecewise-smooth flow completion

Non-local flow neighbors

Seamless blending

